

## model nP4

M.I. nP4-01/18.04  
Cod. ISTR-MInP4ENG01

# Installation Manual

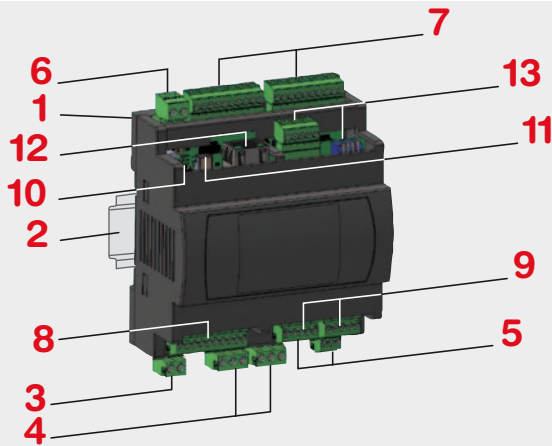
### Contents

- General description
- Accessories
- Installation
- Electrical connections
- Electric safety

## Integrated system, CPU module with on-board I/O

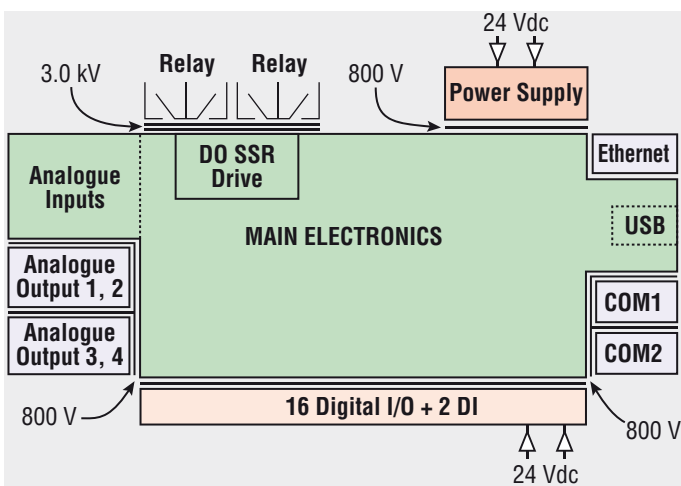


### General description



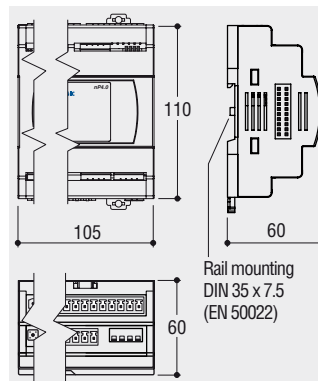
- 1 Model identification label (on the back side of the module);
- 2 DIN RAIL 35 x 7.5 (EN50022);
- 3 X1 24 Vdc Power Supply plug;
- 4 X2 OP1... OP2 Digital Output SPST relay or 24 Vdc SSR drive;
- 5 X3 OP3... OP4 Digital Output SPST relay or 24 Vdc SSR drive;
- 6 X4 COM2 RS485 serial port and SW2 switches for line settings;
- 7 X5 24 Vdc input for D01... D08 when configured as Digital Output;
- 8 X6 D01... D08 configurable DI/DO + 2 DI pulse counters (CNT1, CNT2);
- 9 X7 24 Vdc input + D09... D16 configurable DI/DO;
- 10 X8 5 V Ratiometric, 12 Vdc AI Power and AI1... AI4 universal analog input;
- 11 X9 AO1... AO2 mA or V analog outputs;
- 12 X10 AO3... AO4 mA or V analog outputs;
- 13 Status/diagnostic LEDs (PWR, RUN, MSG, USB, COMS) + Reset Button;

### Isolation scheme



### Installation

#### Dimensions (mm)



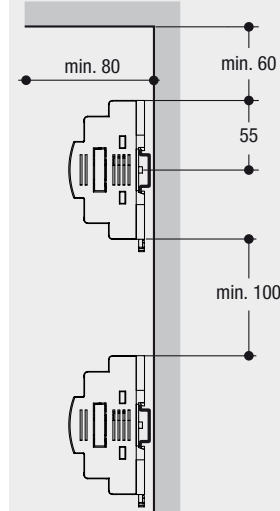
#### Operating conditions

Environmental condition	ΔCe	Suggestion
Operating conditions	Temperature: -20...+50°C Humidity: 5... 95% Rh non condensing	
Special conditions	Temperature: > 50°C Humidity: > 95% RH	Use forced ventilation Warm up
Forbidden conditions	Conducting atmosphere Corrosive atmosphere Explosive atmosphere	Use filter

#### Mounting position

- Mount the module vertically;
- In order to help the air ventilation flow, respect the distances between modules and walls or other modules.

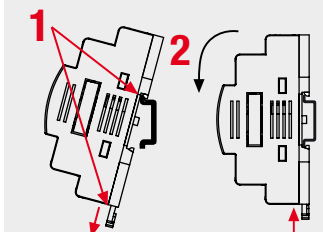
#### Mounting position (mm)



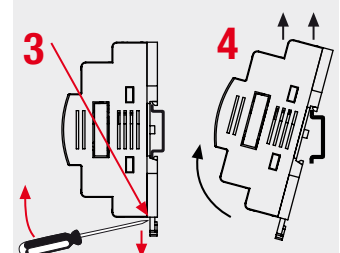
#### Mounting/removing the modules on/from the DIN rail

- 1 Open the 2 spring slides on the lower part of the CPU, clip the upper part of the module to the rail;
- 2 Rotate the module downwards, then close the 2 spring slides;
- 3 Switch OFF the Power Supply. Lower the spring slide by inserting a flat-blade screwdriver as indicated;
- 4 Turn and lift the module upwards to remove the CPU from the DIN rail.

#### Mounting the module



#### Removing the module

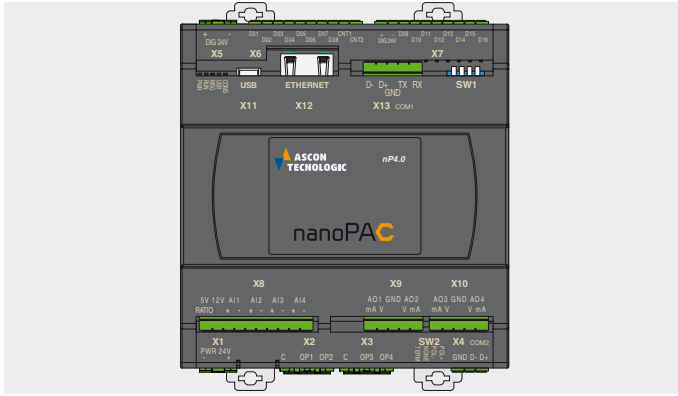


#### Disposal



## Electrical connections

### Terminals connections and plugs



Conn.	Label	Signals
X1	Supply	0 V Power Supply
	24 Vdc	+24 V Power Supply
X2	C	OP1, OP2 common
	OP1	SPST NO pole/SSR drive
	OP2	SPST NO pole/SSR drive
X3	C	OP3, OP4 common
	OP3	SPST NO pole/SSR drive
	OP4	SPST NO pole/SSR drive
X4	GND	
	D-	COM2 - RS485
	D+	
X5	+	For D01... D08 when DO
	-	For D01... D08 when DO

Conn.	Label	Signals
X9	mA	AO1 Current output
	V	AO1 Voltage output
	GND	AO1, AO2 ground
X10	mA	AO2 Current output
	V	AO2 Voltage output
	GND	AO2, AO3 ground
X11	mA	AO3 Current output
	V	AO3 Voltage output
	GND	AO3, AO4 ground
X12	mA	AO4 Current output
	V	AO4 Voltage output
	GND	AO4, AO5 ground
X13	USB	MicroUSB type port

Description	Plugs of all terminals
Flexible cable section:	Pitch 5 mm: 0.2... 2.5 mm <sup>2</sup> (AWG24... AWG12) Pitch 3.5 mm: 0.14... 1.5 mm <sup>2</sup> (AWG28... AWG16)
Stripped wire	<b>Screw:</b> 7mm
Flat blade screwdriver	Pitch 5 mm: 0.6 x 3.5 mm Pitch 3.5 mm: 0.4 x 2.5 mm
Tightening torque	Pitch 5 mm: 0.5... 0.6 Nm Pitch 3.5 mm: 0.22... 0.25 Nm

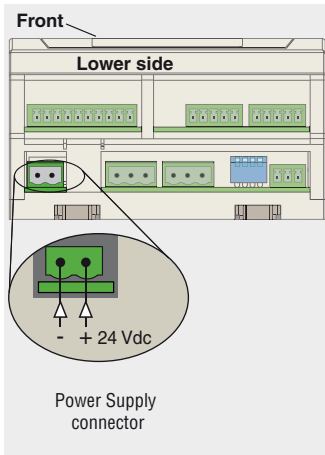
#### Technical data:

- The green terminals are male connectors (pitch 3.5 or 5 mm), the correspondent female connectors have screw or spring terminals for connecting the wires;
- Made with self extinguishing material as required by UL94 V0 standard;
- Overvoltage category/pollution degree II/2;
- Max. load current/section 8A/2.5mm<sup>2</sup> at 65°C;
- Test pulse voltage: 4 kVp.
- ⚠ Make sure that the overall current absorption (modules and field devices) matches the power supply;
- ⚠ In order to avoid excessive voltage drops, install the most power consuming modules closer to the power supply.

Conn.	Label	Signals
X6	D01... D08	Configurable Digital I/O
	CNT1... 2	Digital pulse count
X7	+	For D09... D16 when DO
	-	For D09... D16 when DO
X8	D09... D16	Configurable Digital I/O
	5V	5 V power for ratiometric inputs
	12V	12 V power for sensor excitation
X9	A1... A4	Universal analog input channels
	(+ -)	

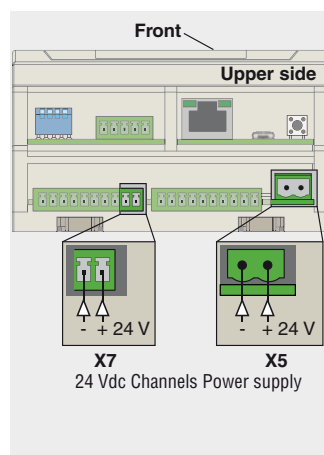
Conn.	Label	Signals
X12	Ethernet	RJ45 10/100 Ethernet port
	D-	COM1 - RS485
X13	D+	COM1 - RS485
	GND	Ground
	Tx	COM1 - RS232
X14	RX	COM1 - RS232

#### X1 - Power supply



- Connector **X1**: 24 VDC (-10... +15%), 15 W max..

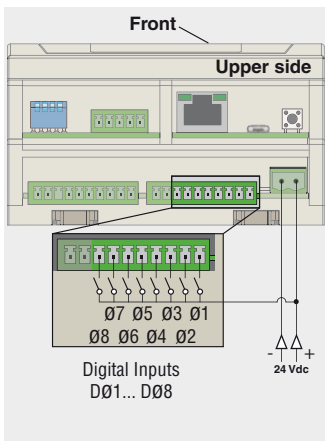
#### X5/X7 - Power supply for Digital Channels



- **X5** and **X7** connectors ( + and - terminals): 24 Vdc Digital Channels Power Supply;
- These 2 power supply terminals are internally connected.

- ⚠ The amount of current that must be supplied to this connectors depends by the number of channels configured as outputs (D01... D16).

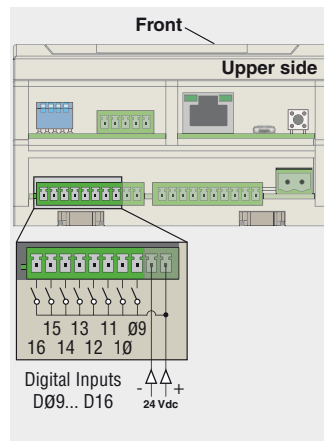
#### X6 - Digital Inputs D01... D08 Connections



- Example of connection when D01... D08 are configured as Digital Inputs;
- Isolation: 800V between the Digital Inputs and the Main Electronics;

- ⚠ For proper electrical connection, refer to **X5/X7 - Power supply for Digital Channels**.

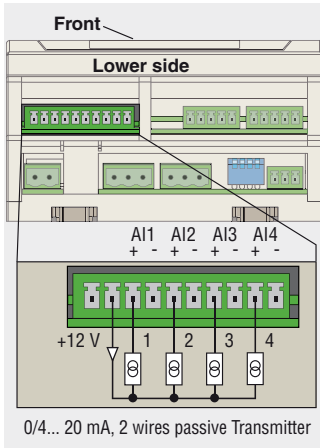
#### X7 - Digital Inputs D09... D16 Connections



- Example of connection when D09... D16 are configured as Digital Inputs;
- Isolation: 800V between the Digital Inputs and Main electronics;

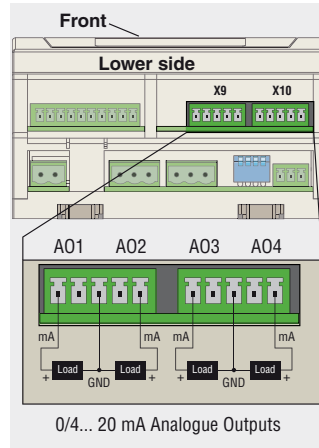
- ⚠ For proper electrical connection, refer to **X5/X7 - Power supply for Digital Channels**.

## X8 - AI1... AI4 Analogue Input connection

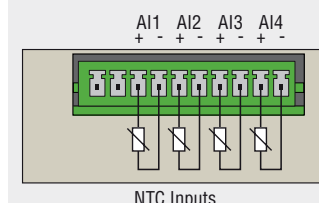
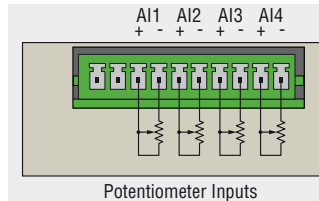
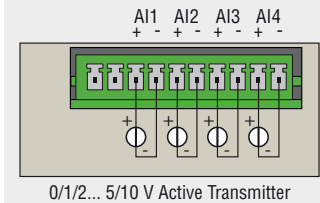
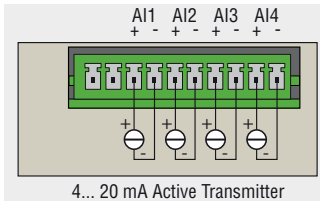


- For the analogue input, respect the polarity shown;
- Pay attention to connect the power source to each external sensor;
- Type: 0/4... 20 mA, 0/1... 5 V, 0/2... 10 V, T/c (J, K, L, N, R, S, T) PT100 (2 wires), PT1000, NTC, Potentiometer, Ratiometric (5 V);
- Resolution: 16 bit;
- Accuracy: 0.1% of span (linear inputs), 0.2% (temperature);
- Input impedance: 120 k $\Omega$  (V), <200  $\Omega$  (mA).

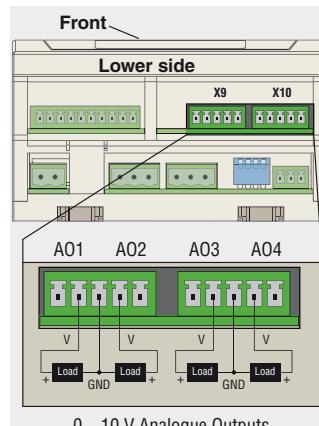
## X9, X10 - AO1... AO4 Current Analogue Output Connections



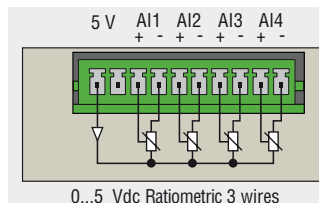
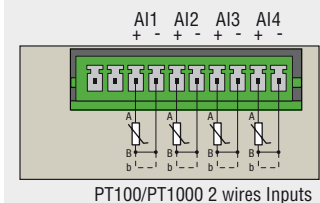
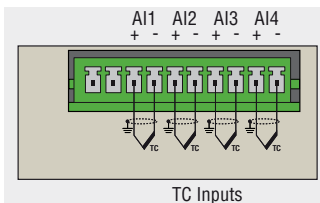
- Respect the polarity shown;
- Type: 0/4... 20 mA;
- Load: < 500  $\Omega$ ;
- Resolution: 12 bit;
- Accuracy: 0.1%;
- Isolation: 800V between the Analogue Outputs and the Main Electronics.



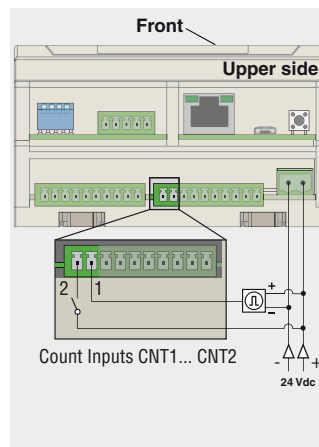
## X9, X10 - AO1... AO4 Voltage Analogue Output Connections



- Respect the polarity shown;
- Type: 0/4... 20 mA, 0/1... 5 V, 0/2... 10 V;
- Load: > 1 k $\Omega$ ;
- Resolution: 12 bit;
- Accuracy: 0.1%;
- Isolation: 800V between the Analogue Outputs and the Main Electronics.



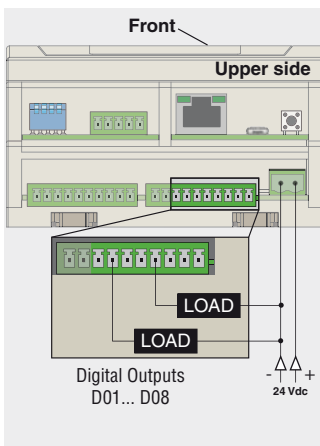
## X6 - CNT1... CNT2 Pulse Count Inputs Connections



- Both channels can manage signals up to 5 kHz;
- Isolation: 800V between the Count Input channels and Main Electronics.

**⚠** For proper electrical connection, refer to **X5/X7 - Power supply for Digital Channels**.

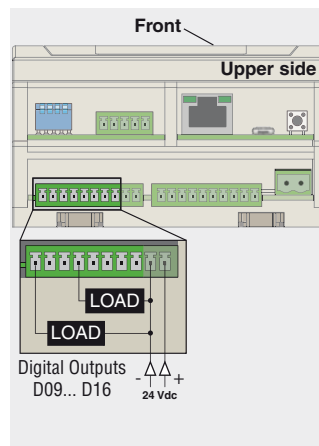
## X6 - D01... D08 Digital Outputs Connections



- The Digital Outputs number of the terminals are: D01... D08
- The 8 output loads should not exceed **0.7 A each**;
- In the drawing are connected only 2 loads as an example;
- Isolation: 800V between the Digital Outputs and the Main Electronics.

**⚠** For proper electrical connection, refer to **X5/X7 - Power supply for Digital Channels**.

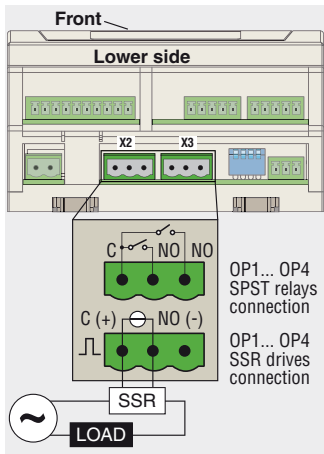
## X7 - D09... D16 Digital Outputs Connections



- The Digital Outputs number of the terminals are: D09... D16;
- The 8 output loads should not exceed **0.7 A each**;
- In the drawing are connected only 2 loads as an example;
- Isolation: 800V between the Digital Outputs and the Main Electronics.

**⚠** For proper electrical connection, refer to **X5/X7 - Power supply for Digital Channels**.

## X2, X3 - Digital outputs OP1... OP4: SPST Relays/SSR drive



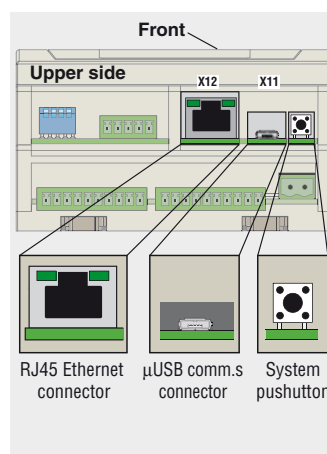
### Relays:

- Rate: 2 A (for resistive loads);
- Isolation: 3 kV rms between each channel and Power Supply and between each channel and Main electronics.

### SSR drives:

- Voltage output 0/12 Vdc;
- Respect the polarity shown;
- Output not isolated.

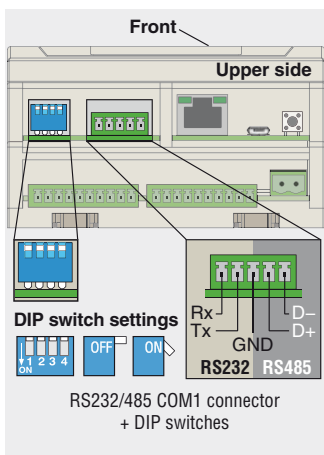
## X11, X12 - USB port + Ethernet + System pushbutton



- The Ethernet connection is made through a standard J45 connector;
- The 2 green LEDs near the Ethernet connector show the port status and the communication traffic;
- μUSB type AB port (X11) to connect a flash drive (Firmware, system files upload/download or data logging);
- System pushbutton.

**!** The system pushbutton performs different operations accordingly to the system status but does not restart the CPU or the 1131 application.

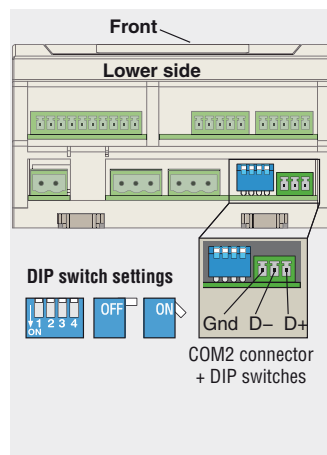
## X13 - COM1 RS232/485 Serial Communications Port



- To connect an RS232/485 terminal (also for setup purposes). Through this port, using the Modbus protocol (master/slave) or serial ASCII the PLC can connect a fieldbus network;
- Isolation from Main electronics: 800 V (**optional**).
- RS485 (COM1) line settings can be configured using the specific DIP switches:

SW	Description	Default
1	110 Ω line termination	OFF
2	Not used	
3	Line polarization Pull-Down	OFF
4	Line polarization Pull-Up	OFF

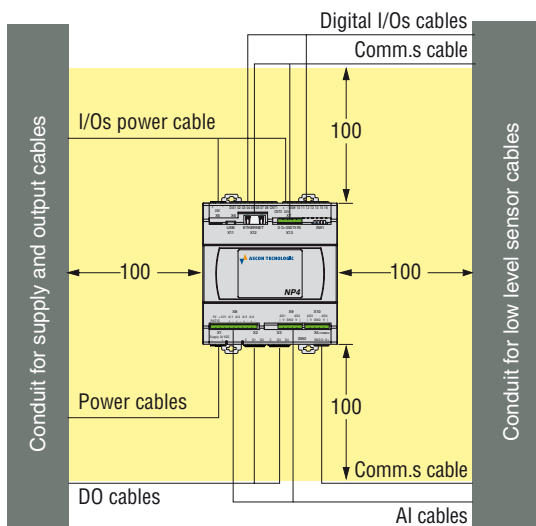
## X4 - COM2 RS485 Serial Communication Port



- RS485 port to connect a fieldbus network using the Modbus protocol (master/slave) or serial ASCII;
- Isolation from Main electronics: always 800 V.
- RS485 (COM2) line settings can be configured using the specific DIP switches:

SW	Description	Default
1	110 Ω line termination	OFF
2	Not used	
3	Line polarization Pull-Down	OFF
4	Line polarization Pull-Up	OFF

## Suggested wires routing



Despite the fact that the instrument has been designed to work in an harsh and noisy environment, it is strongly recommended to follow the following suggestions.

All the wiring must comply with the local regulations.

The supply wiring should be routed away from the power cables. Avoid to use electromagnetic contactors, power relays and high power motors nearby.

Avoid power units nearby, especially if controlled in phase angle. Keep the low level sensor input wires away from the power lines and the output cables.

Power lines and output cables must also be at **100 mm** (min.) away from the CPU. If this is not achievable, use shielded cables on the sensor inputs, with the shield connected to earth at one side only.



### Warning!

Whenever a failure or a malfunction of the device may cause dangerous situations for persons, things or animals, please remember that the plant must be equipped with additional devices which will guarantee safety.

## How to order

### NP4 = CPU of the Programmable Logic Controller

#### A: Display

- = No Display
- D = Display (available soon)

#### B: Optional Digital Outputs

- = No Digital Outputs
- M = 2 Relay + 2 SSR drive
- R = 4 Relay
- S = 4 SSR Drive

#### C: Analogue Inputs

- = No Analogue Inputs
- 4 = 4 Universal AI
- 5 = 4 Universal and Ratiometric AI

#### D: Analogue Outputs

- = No Analogue Output
- 2 = 1 isolated module with 2 not isolated AOs
- 4 = 2 isolated modules with 2 not isolated AOs each

#### E: Digital Channels

- = No Digital Channels
- 88 = 8 Inputs + 8 Outputs + 2 DI Pulse Counters
- 16 = 16 configurable + 2 DI Pulse Counters

#### F: Field bus

- E = Ethernet

#### G: Communication Ports

- = No Communication Ports
- 1S = COM1
- 1I = Isolated COM1
- 2S = COM1 + Isolated COM2
- 2I = Isolated COM1 + Isolated COM2
- 4I = Isolated COM2

NP4 - - - - - E